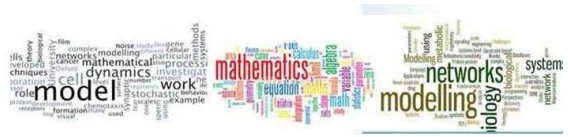


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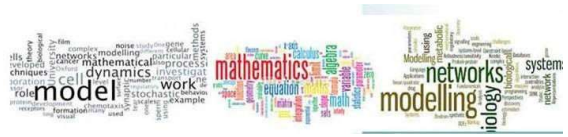
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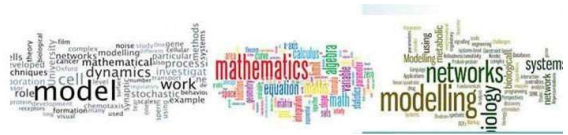
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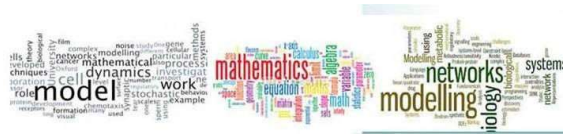
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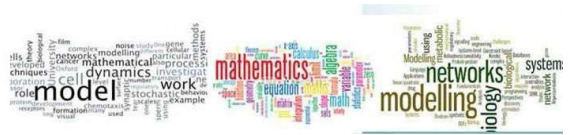


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First Order Differential Equations with Applications to Security Service Companies

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ABSTRACT

First order differential equations is of interest to Every sectors because of the possibility in it to investigate a wide variety of problems in the physical, biological and social sciences. First order differential equations are powerful tools in Sciences and engineering, such that if carefully and effectively applied to real life problems will yield good estimate results for prediction. The problem of a company engaging in security services is modeled into a first order differential equation and the resulting simplified mathematical equation is then solved. The company expected rate of decay (death, retirement etc.) is then substituted and estimated years of expansion is determined, this form the list of some tested years. It was discovered that the result obtained is a good estimation for prediction. This paper also gives room for any other rate of decay to be tested and expected number of years to be determined..

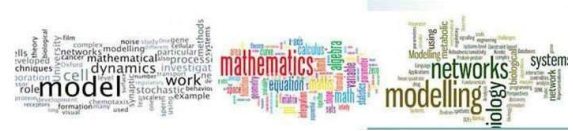
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1. INTRODUCTION

According to pack (1960), a first order differential equation is a relation between the dependent variable independent variable t and the derivative of the dependent variable with respect to the

independent variable (i.e. $\frac{dx}{dt}$).



Suppose we denote $\frac{dx}{dt}$ by \dot{x} , we assume that in some domain D , we may express \dot{x} as a function of t and x , thus

$$\dot{x} = f(t, x) \quad (1.1)$$

Where f is a given function of two variables. Any function $x = \phi(t)$. Which with its derivative y' identically satisfies equation (1.1) is called a solution, and our objective is to determine whether such functions exist and if so, how to find it.

Pack(1960), stated further that the simplest type of first order differential equation occurs when f depends only on t , in this case

$$\dot{x} = f(t) \quad (1.2)$$

Therefore, we seek a function $x = \phi(t)$ whose derivative is the given function f . From the elementary calculus we know that ϕ is an anti-derivative of f and we write

$$x = \phi(t) = \int_{t_0}^t f(s)ds + c \quad (1.3)$$

Where c is an arbitrary constant.

If we return to the solution of equation (1.1), Although there is no satisfactory general method of writing down the solutions of this equation, therefore, the solution depends on the class of the first order differential equation as a result, we will present few methods, each of which is applicable to a certain class of equations of the form (1.1).

1.1 Methods Of Solving First Order Differential Equation

1.1.1 Separation of Variables:

Diprime (1976) stressed that this method is one of the most commonly used method.

If
$$\frac{dx}{dt} = f(t) \quad (1.4)$$

Where $f(t)$ is a given function of t . We know from calculus that if

$$x(t) = \int_a^t f(t^1)dt \quad (1.5)$$

The solution can be immediately obtained in the form of



$$\int f(t)dt + \int g(x)dx = c$$

1.1.2 Equation Reducible to Separable Type

Burghes (1980) made it known that certain equations of the form

$$g(t, x)dx = f(t, x)dt$$

That are not separable can be made separable by a change of variable.

This can always be done, if the ratio of $\frac{f(t, x)}{g(t, x)}$ is a function of $\frac{x}{t}$.

Let $u = \frac{x}{t}$ and the function of $\frac{x}{t}$ be $h(u)$, so that

$$\frac{dx}{dt} = \frac{f(t, x)}{g(t, x)} = h(u)$$

Since f is function of t , so is u . it follows that

$$x(t) = tu(t) \text{ and}$$

$$\frac{dx}{dt} = u + t \frac{du}{dt}$$

Thus the differential equation can be written as

$$u + t \frac{du}{dt} = h(u) \text{ or } t \frac{du}{dt} = h(u) - u$$

Clearly, it is separable

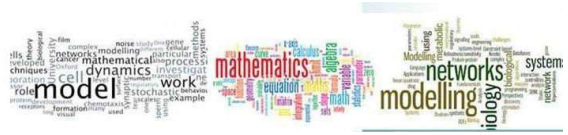
$$\frac{du}{h(u) - u} = \frac{dt}{t}$$

So we can solve for $u(t)$ and the solution of the original differential equation is simply $x = tu(t)$.

1.1.3 Exact Differential Equations

Suppose we want to find a differential equation that represents the following family of curves

$$F(t, x) = c$$



First let us look at two nearby points (t, x) and $(t + \delta t, x + \delta x)$, both on a specific curve of the family. If the curve is characterized by $c = k$, then

$$F(t, x) = k, f(t + \delta t, x + \delta x) = k$$

Clearly, the difference between the two is equal to zero. i.e $f(t + \delta t, x + \delta x) - f(t, x) = 0$

This difference can be written in the form of

$$f(t + \delta t, x + \delta x) - f(t, x) = f(t + \delta t, x + \delta x) - f(t, x + \delta x) + f(t, x + \delta x) - f(t, x) \quad (1.6)$$

With the understanding that δt and δx are approaching zero as a limit. We can equally use the definition of partial derivative

$$f(t + \delta t, x + \delta x) - f(t, x + \delta x) = \frac{\partial f}{\partial t} \delta t, \text{ and } f(t, x + \delta x) - f(t, x) = \frac{\partial f}{\partial x} \delta x$$

To write (1.6) as

$$\delta f = \frac{\partial f}{\partial t} \delta t + \frac{\partial f}{\partial x} \delta x \quad \text{or} \quad \partial f = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} dx$$

This is known as total differential, since $\delta f = 0$, so we have

$$\frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} dx = 0 \quad (1.7)$$

This is the differential equation representing the family of curves $F(x, y) = c$, in other words the Solution of the differential equation in the form (1.7) is given by $F(x, y) = c$.

Now, let $\frac{\partial f}{\partial t} = f(t, x)$ and $\frac{\partial f}{\partial x} = g(t, x)$ (1.8)

Any equation of the form $f(t, x)dt + g(t, x)dx = 0$ that satisfies

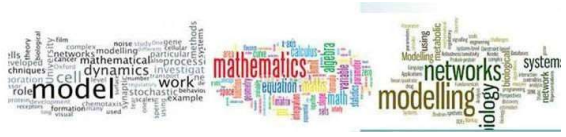
$$\frac{\partial}{\partial x} f(t, x) = \frac{\partial}{\partial t} g(t, x) \text{ is known as an exact equation.}$$

1.1.4 Integrating Factors

According to Balogun (2006), Factor, which when multiplied with a non-exact differential equation Makes exact, is known as an integrating factor.

For example, the equation

$$xdt + (t^2x^3 + t)dx = 0 \text{ is not exact, if, however, we multiply it by } (xy)^{-2}, \text{ the}$$



Resulting equation

$\frac{1}{t^2 x} dt + (x + \frac{1}{ty^2}) dx = 0$ is exact, since $\frac{\partial}{\partial x} (\frac{1}{t^2 x}) = -\frac{1}{t^2 x^2}$ and

$$\frac{\partial}{\partial t} (x + \frac{1}{ty^2}) = -\frac{1}{t^2 y^2}$$

Hence by definition $(xy)^{-2}$ is an integrating factor.

Olagunju (2006): an integrating factor exists for every differential equation of the form

$$f(t, x)dt + g(t, x)dx = 0 .$$

Unfortunately, no general rule is known to find it. For certain special type of differential equations, integrating factor can be found systematically.

We assume that $f(t, x)dt + g(t, x)dx = 0$ is not exact differential equation, we wish to find an integrating factor μ so that

$\mu f(t, x)dt + \mu g(t, x)dx = 0$ is exact. For this equation to be exact, it must satisfy the condition

$$\frac{\partial}{\partial x} (\mu f) = \frac{\partial}{\partial t} (\mu g) \text{ which gives}$$

$$\mu (\frac{\partial f}{\partial x} - \frac{\partial g}{\partial t}) = \frac{\partial \mu}{\partial t} g - \frac{\partial \mu}{\partial x} f \tag{1.9}$$

Now we consider the following possibilities:

The integrating factor is a function of t only. In this case, (1.9) becomes

$$\frac{1}{g} (\frac{\partial f}{\partial x} - \frac{\partial g}{\partial t}) = \frac{1}{\mu} \frac{\partial \mu}{\partial t}$$

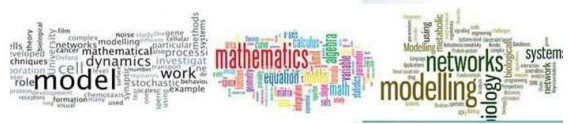
If the left-hand of this equation is also a function of x only, then

$$\frac{1}{g} (\frac{\partial f}{\partial x} - \frac{\partial g}{\partial t}) = G(t)$$

Then clearly $\frac{d\mu}{\mu} G(t) dt$

Which gives

$$\ln \mu = \int G(t) dt \text{ or } \mu = e^{\int G(t) dt}$$



Thus, from the result above, the target will be met by the beginning of the 8th years, given that the rate of reduction (decay) is 0.04 . That is to say that at the beginning of the 8th year we would have 504 security men which is very close to the target which is 500. Observation/challenges with this, the management discovered that the decision on the expansion is incorrect. What happens to the excess security men from the beginning of the 8th year through the tenth year?

Thus, the management is to be advised to reduce the rate of steady expansion per year, so as to meet his target at the tenth year when the number of security men on ground will be the same as those needed by his customers. This reduction rate in other to meet the target is the challenge ahead of the management. If the management finds it difficult then she could stop expansion after the 8th year and pray that the reduction factor δ tends to zero for the last two years, so that she has nearly 504 security men at the tenth year.

3. CONCLUSION

The importance of first order differential equations is clearly spelt out in this case study. In ordinary sense, the management's decision in expanding the security service steadily year by year, spreading the new security men out over each year as 10,20,30 . . . etc. up to the 10years and the demand projection survey that their demand will doubled over the next 10 years would have yielded incorrect result, if the weapon "first order differential equation" have not been employed.

Assuming the management's expected rate of decay is:

$$\delta = 0.03 \text{ or } \delta = 0.05 \text{ or } \delta = 0.06 \text{ etc}$$

It is possible to find out the estimated number of years for the number of security men to be doubled or tripled



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