

Fig. 5: Nose Feature Points Measurements: (nasal length (n-sn), nasal height (n-hn), and nasal breadth (al-al))
 Source: (Sahni, 2014)

This approach is intrinsically simple with computational efficiency. It involves the measuring of nose breadth (width) (*al-al*) and total length of the nose (*n-sn*) as labelled in figure 5. The nose ridge profile are calculated by the ratio of nasal width to the nasal length multiplied by 100. This is called the nasal index. The Nasal index is mathematically expressed as stated in equation 1 (Hall et al., 2007; Sahni, 2014).

$$\text{Nasal Index} = \frac{\text{width of the nose}(al-al) \times 100}{\text{total nose length}(n-sn)} \quad \dots\dots\dots \text{Equation 1}$$

2.3.2 The Geometric Nasal Proportions (GNP) Approach

The GNP technique involve the process of capturing the geometric vector of the nose. It is measured by calculating the saddle ratio and nose tip ratio. The saddle ratio and the nose tip ratio are combined in a two-element feature vector. These are mathematically represented in equation 2. Figure 6 shows the geometric nasal proportions.

$$\text{Saddle ratio} = \frac{\text{Saddle width}}{\text{Ridge length}}$$

$$\text{Nose tip ratio} = \frac{\text{Nose tip width}}{\text{Ridge length}}$$

..... Equation 2

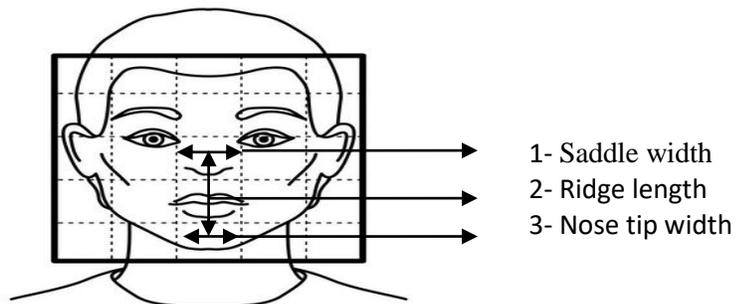


Figure 6: Geometric Nasal Proportions

2.3.4 The Nose Region Segmentation (NRS) Approach

The nose region segmentation is a multistage classifier for face recognition. The method considered the distance between the forehead and mouth top lip with the nose tip which is the closest object to the camera.

3. MATERIALS AND METHOD

3.1 Architectural System Model

The architectural system model for the proposed nose recognition system designed for the work is structured in Figure 8.

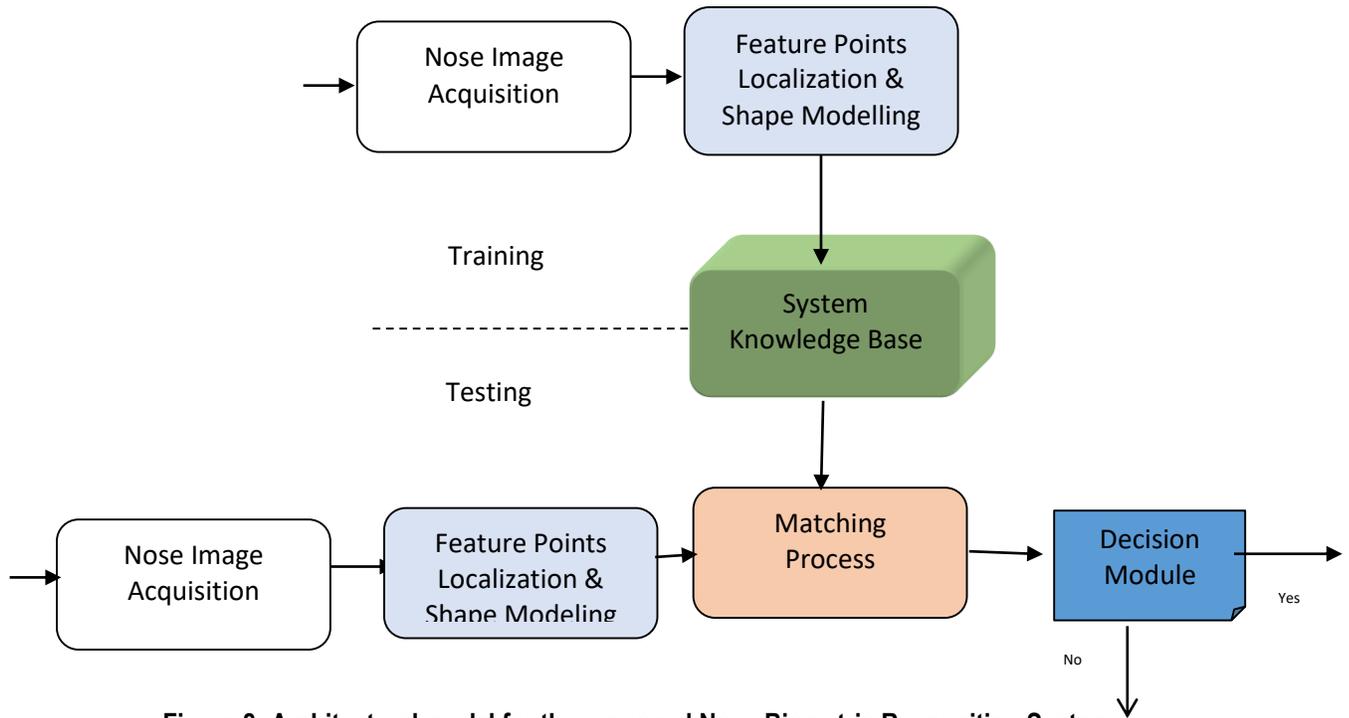


Figure 8: Architectural model for the proposed Nose Biometric Recognition System

The model considered five (5) major modules for its processes. The first module handles the nose image acquisition considering the feature points which can be extracted either photometrically or manually. The second module models the shape of the nose using the two robust techniques considered in this work. The feature point localization procedure is based on the position of the nose tip with other feature points. The third module is the system knowledge base which house the model template where references are drawn during matching process. The data acquired during enrolment are trained and tested to arrive at the final templates stored in the knowledge base. The fourth module is the matching module which compares the template stored in the database during enrolment with that of the pattern obtained for verification. The fifth module authenticates claims from individual enrolled in the system and decides identification or rejection using the automatic detection algorithm presented in Figure 9.

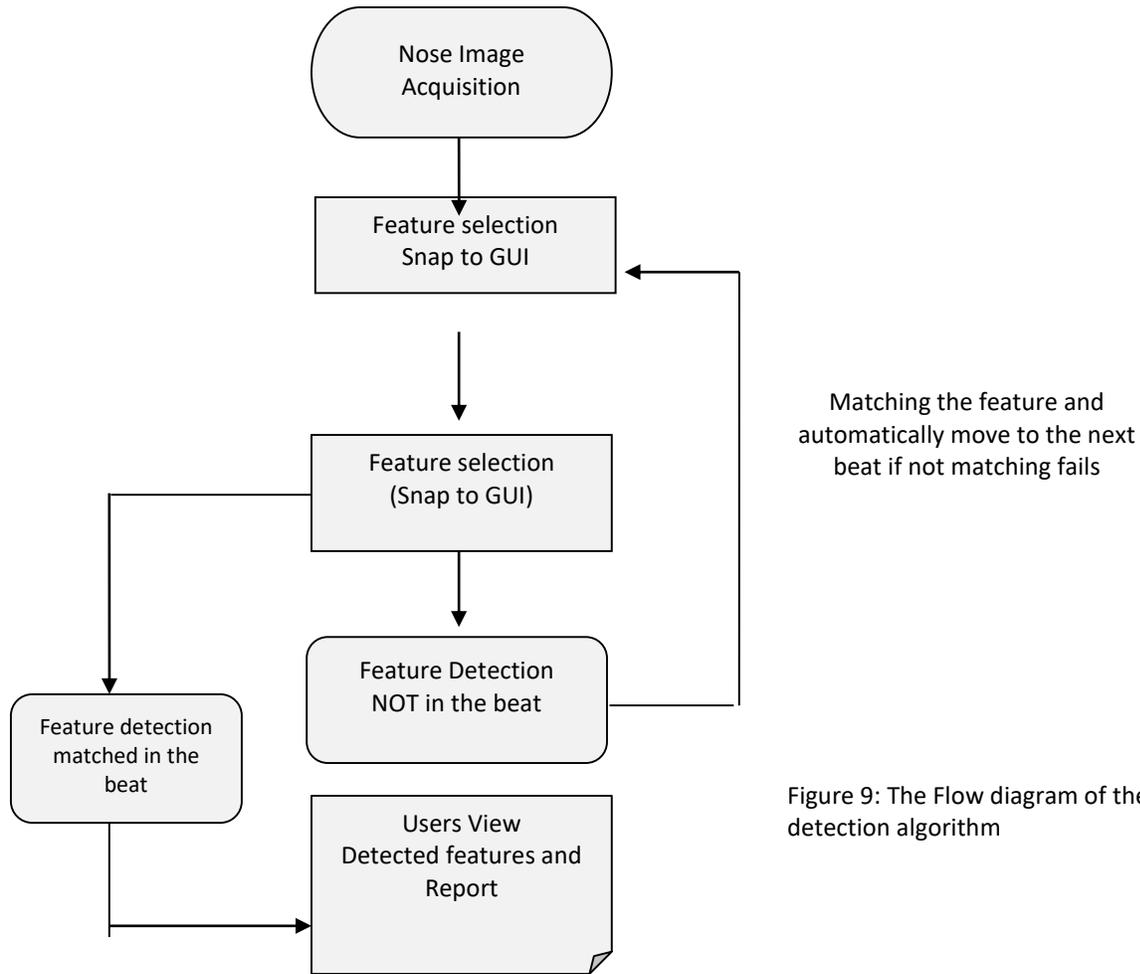


Figure 9: The Flow diagram of the automatic detection algorithm

Fig 9: The Automatic Detection Algorithm

3.2 Data Collection

Nose images used for the study were randomly acquired from 105 adult subjects comprises of (55 males and 50 females) across different tribes in Nigeria. The length, the width of the nose of each subject and other subject's details were considered during enrolment. The data obtained was statistically analyzed, the nasal index and curvature-based landmark detection techniques were computed for each nose captured as shown in Table 1.

3.3.1 Login Screen: The login screen is mainly to register and authenticate users in order to gain access to the system.

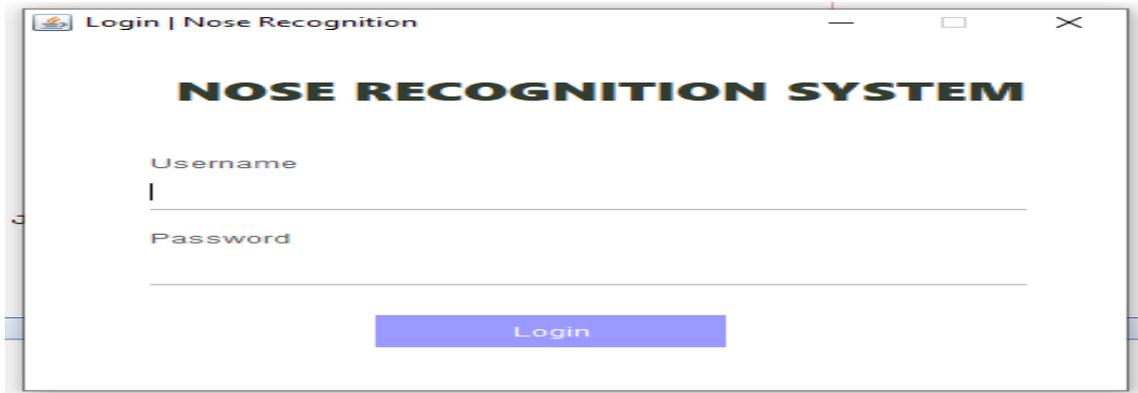


Figure 10: Login Screen

3.3.2 Main Menu:

The main menu provides users with the enrolment and verification process options as shown in Figure 11. User can as well view previously saved information using “the view saved data” button.

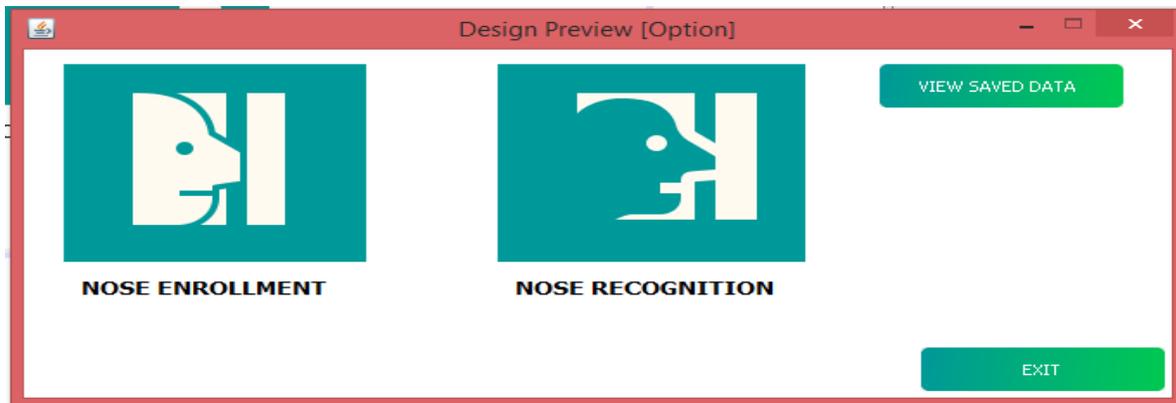


Figure 11: Design View of the Main Menu

Figure 14 shows the sampled information previously saved in the system database.

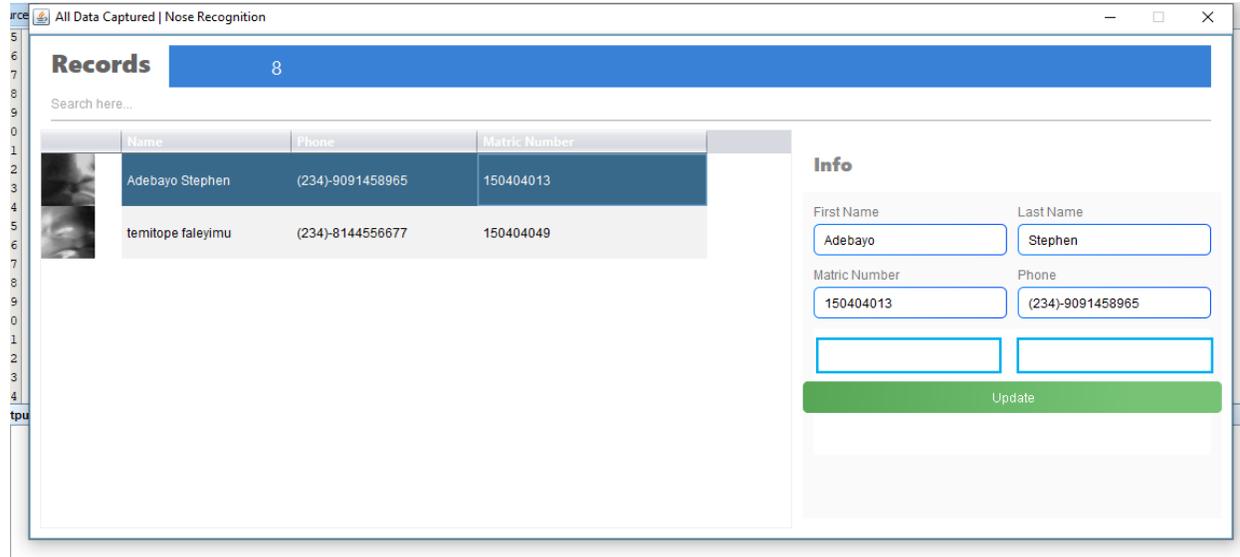


Figure 14: Sampled information Previously Saved in the System Database.

4. EXPERIMENTAL RESULTS

Table 2 shows the results of the system performance with respect to the two recognition techniques considered in this work (Nose Ridges Profile (NRP) and Curvature based landmark detection (CBLD)) techniques. The approaches showed a good performance of 98 % and 96% in terms of average recognition rate (ARR) with average recognition time taken of 17 seconds and 1 seconds respectively. The performance metric also considers the FAR and FRR with an average of 1 % each with respect to both the CBLD and NRP respectively.

Table 2: Results of the system performance with respect to the two recognition techniques considered

S/N	Personality	Nose Ridges Profile		Curvature-based landmark detection	
		Average Recognition Rate %	Time Taken (seconds)	Average Recognition Rate %	Time Taken (seconds)
1	P1	97	1	97	16
2	P2	96	2	98	17
3	P3	95	1	97.5	17
4	P4	97	1	98	16
5	P5	96	2	97	17



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